Maps for fleet tracking



Senseforce Rocket update 1.5.7 provides a great new tool for fleet management: Maps. Track the position of your whole fleet by displaying your machinery on their according positions. Use the interactive map modes to zoom in/out and use drag & drop style map navigations.

Alternatively, show the movement path of the last hours of your machinery to track position and be able to tell exactly where your machine was on which specific date and time.

Feature overview:

- Drag & drop map
- Full screen map mode
- Movement path mode: Track movement of on machine
- Marker mode: show the current position of different machines
- Direction: Display the direction of your machinery in marker mode
- Display additional on-click information for every marker

Step by step - movement path

- 1. Everything starts with an Analytics Query. Create a query with at least the following columns:
 - a. Thing
 - b. Timestamp
 - c. Longitude
 - d. Latitude

Set a Filter to the Thing-column so that the path of only one thing is illustrated.

Make sure, to order the Timestamp-column descending to get the latest values on top of your dataset.

🖽 Data set				
Thing thing	×	Timestamp 🗙 timestamp	Longitude X MDE1_2.MachineNumber	Latitude X MDE1_2.MachineNumber
Filter = WolfurtSaw1 +	×	Filter	Filter +	Filter +
Aggregation	•	Aggregation	Aggregation	Aggregation
None Sort	•	None Sort	None 💌	None Sort
Select 💌		Descending 👻 Group column by	Select 👻	Select 💌
Group column Show data		None Show data	Group column Show data	Group column Show data
# Text		timestamp	Nummer	Nummer

2. Create a new Widget, "Add new Element" and select "Map" as Element type.

Widgets		
Elements	General	
 Main Value 	Header	Unnamed Element
Unnamed Element Add new Element 1.	Show Header in Widget	✓
	Row Span	1
	Column Span	1
	Value Type	2.
	Fixed DataSource Table Chart ProgressBar In	mage 💽 Map
	Map Settings Parameters	

 Select the Data Source (analytics query or script) for your map – like in any other widget element. Furthermore, select the column of the data source which should be used as longitude and which column should be used as latitude.

Map Settings Parameters	
Query Type 1.	AnalyticsQuery Script
Query	Select > C
Мар Туре 2.	Path Marker
Longitude Column	Select
Latitude Column	Select >
Center on first Point	\checkmark
Update mode	None •
Initial Zoom	13
Line Color	
Arrowhead Color	
Refresh Time (sec)	0
Limit Rows	OFF

- 4. (Optional): Set the color of the movement path line and the movement direction color.
- 5. (Optional): Set the zooming mode settings:
 - a. <u>Center on first point</u>: The map is centered on the first path point
 - b. <u>Update mode</u>: Defines, how the map behaves, if new position data arrive.
 - i. <u>Keep in bounds</u>: The zoom and map position is adjusted, to keep all path points within the visible range
 - ii. <u>Center on last point</u>: The map is adjusted to automatically always be positioned to display the latest point
 - iii. <u>None</u>: The zoom as well as map position is not automatically adjusted
 - c. <u>Initial zoom:</u> Set the initial zoom range (0 ... min zoom setting)

Step by step - marker mode

Marker mode allows to display the last position of several machines and furthermore provides an option to display the direction of the machinery.

- 1. Again, everything starts with an Analytics Query. Create a query with at least the following columns:
 - a. Thing
 - b. Timestamp
 - c. Longitude
 - d. Latitude

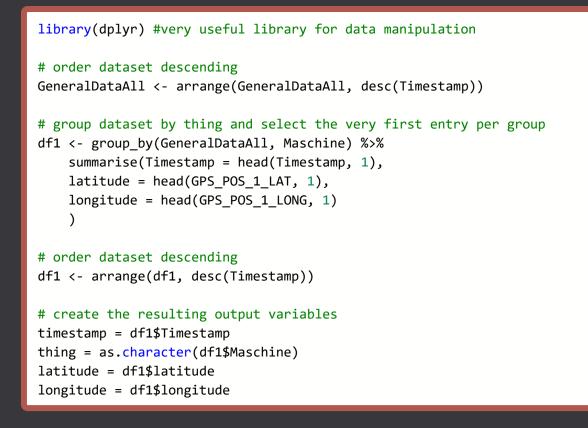
Order the Timestamp-column descending to get the latest values on top of your dataset.

🆽 Data	set						
₹ ♥	Maschine X [Example]event.thing		Timestamp X [Example]event.timestamp		GPS_POS_1_LAT X Example.GPS_POS_1_LAT	GPS_POS_1_LONG X Example.GPS_POS_1_LONG	
	Filter		Filter		Filter	Filter	
	None 🔹	×	None	×	+	+	
	Aggregation None Sort Select		+				
			Aggregation None Sort Descending Group column by		Aggregation	Aggregation None Sort Select	
					None 🔻		
					Sort		
					Select 🔻		
	Group column		None		Group column	Group column	
	✓ Show data		✓ Show data		✓ Show data	✓ Show data	

Create a script which calculates the latest incoming value for latitude and longitude.

Assuming, our Analytics query used as script input was called "GeneralDataAll" and the above illustrated columns were combined to our input data set, the script looks as follows: Simply copy the script to your script editor, use the previously created analytics query as input and define the following output variables:

- timestamp (type: timestamp)
- thing (type: string)
- latitude (type: double, decimal places: 6)
- longitude (type: double, decimal places: 6)



Please be aware, that the analytics query columns must match the script variable names -> The analytics query must be named **GeneralDataAll**, the thing-column must be named **Maschine**, the timestamp-column must be named **Timestamp**, the latitude column must be called **GPS_POS_1_LAT** and the longitude **GPS_POS_1_LONG**. Rename the according variables in the script, if the naming deviates from the above stated.

3. Create a new Widget, "Add new Element" and select "Map" as Element type.

Widgets		
■ Widget List > New Widget		
Elements	General	
 Main Value 	Header	Unnamed Element
Unnamed Element	Show Header in Widget	✓
 + Add new Element 1. 	Row Span	1
	Column Span	1
	Value Type Fixed DataSource Table Chart ProgressBar In	2. nage • Map
	Map Settings Parameters	

 Select "Marker" as "Map Type" (1), choose script as query type and select the newly created scrip as data source (2). Set the longitude and latitude column (3).

Map Settings	Para	met		
Query Type		2.	AnalyticsQuery Script	7
Query			Select	•
Мар Туре		1.	Path Marker	
Longitude Colu	umn	3.	Select	•
Latitude Colum	n		Select	•
Direction Colur	mn	4.	Select	•
Popup Info Col	lumn		Select	•
Update mode			None	•
Initial Zoom			13	•
Refresh Time (s	sec)		0	•
Limit Rows			OFF	

Optionally, select a column for direction display and on-click popup info. (4)

- 5. (Optional): Set the zooming mode settings:
 - a. <u>Update mode</u>: Defines, how the map behaves, if new position data arrive.
 - i. <u>Keep in bounds</u>: The zoom and map position is adjusted, to keep all path points within the visible range
 - ii. <u>Center on last point</u>: The map is adjusted to automatically always be positioned to display the latest point
 - iii. <u>None</u>: The zoom as well as map position is not automatically adjusted
 - b. <u>Initial zoom:</u> Set the initial zoom range (0 ... min zoom setting)

End result

